INTRODUCTION 00000 0000000000000 0000 Transmission Probability 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

MCMC I Methods Introduction

Vladimir Minin, Kari Auranen, M. (Betz) Elizabeth Halloran

SISMID 2017 University of Washington Seattle, WA, USA

July 13, 2017

0			

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY 0000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

Transmission Probability 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

◆□▶ ◆□▶ ◆□▶ ◆□▶ ●□

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

INTRODUCTION • 0000 • 00000000000 • 0000 TRANSMISSION PROBABILITY 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

Prior, likelihood, and posterior

- Let
 - $y = (y_1, \ldots, y_n)$: observed data
 - $f(y|\theta)$: model for the observed data, usually a probability distribution
 - θ : vector of unknown parameters, assumed a random quantity
 - $\pi(\theta)$: prior distribution of θ
- The posterior distribution for inference concerning θ is

$$f(\theta|y) = \frac{f(y|\theta)\pi(\theta)}{\int f(y|u)\pi(u)du}.$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ ○○○

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

Posterior and marginal density of y

- The integral $\int f(y|u)\pi(u)du$, the marginal density of the data y, does not depend on θ .
- When the data y are fixed, then the integral can be regarded as a normalizing constant C.
- In high dimensional problems, the integral can be very difficult to evaluate.
- Evaluation of the complex integral $\int f(y|u)\pi(u)du$ was a focus of much Bayesian computation.

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

$Advent \ of \ MCMC \ Methods$

• With the advent of the use of Markov chain Monte Carlo (MCMC) methods,

 \longrightarrow one could avoid evaluating the integral, making use of the unnormalized posterior density.

 $f(\theta|y) \propto f(y|\theta)\pi(\theta).$

• Equivalently, if we denote the likelihood function or sampling distribution by $L(\theta)$, then

 $f(\theta|y) \propto L(\theta)\pi(\theta).$ posterior \propto likelihood \times prior

• We will show how this works.

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Other Uses of MCMC Methods

- Can simplify otherwise difficult computations.
- Sometimes a likelihood would be easy to evaluate if some data had been observed that was not observed or is unobservable.
- Examples:
 - infection times,
 - time of clearing infection,
 - when someone is infectious,
 - chains of infection.
- MCMC methods can be used to augment the observed data to make estimation simpler.

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

Likehood and Data Transforms Prior to Posterior

• Likelihood and data take prior to posterior:



• Bayesian data analysis is a study of the transformation.

 Transmission Probability 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

◆□▶ ◆□▶ ◆□▶ ◆□▶ ●□

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Transmission probability

- *p* is the probability an infective infects a susceptible: transmission probability
- q = 1 p is the probability a susceptible escapes infection when exposed to an infective: escape probability
- Transmission versus escape ? which is the "success" and which the "failure"?
- Given there are *n* exposures, and *y* infections, what is the estimate of the transmission probability?
- Given there are n exposures, and n y escapes, what is the estimate of the escape probability?

 Transmission Probability 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

Chain-binomial model

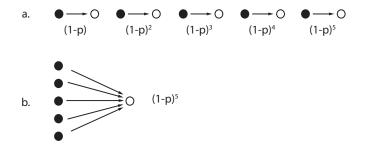
- Assume independent households
- One person in each household introduces the infection into the household (index case).
- Infections occur within households in generations of infection (discrete time).
- *p* is the probability an infective infects a susceptible in a household in a generation
- q = 1 p is the probability a susceptible escapes infection when exposed to an infective in a household

 TRANSMISSION PROBABILITY 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲冊 ▶ ▲ ヨ ▶ ▲ ヨ ▶ ● の Q @

Reed-Frost Chain Binomial Model

Figure : Independent exposures = independent Bernoulli trials



 TRANSMISSION PROBABILITY 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

Chain Binomial Model

Table : Chain binomial probabilities in the Reed-Frost model in N households of size 3 with 1 initial infective and 2 susceptibles, $S_0=2,\,l_0=1$

				Final
Chain		at	at	number
probability	Frequency	p=0.4	p=0.7	infected
q^2	<i>n</i> ₁	0.360	0.090	1
2pq ²	<i>n</i> ₁₁	0.288	0.126	2
2p ² q	<i>n</i> ₁₁₁	0.192	0.294	3
<i>p</i> ²	<i>n</i> ₁₂	0.160	0.490	3
1	N	1.00	1.00	
	probability q^2 $2pq^2$	probabilityFrequency q^2 n_1 $2pq^2$ n_{11} $2p^2q$ n_{111} p^2 n_{12}	probabilityFrequency $p=0.4$ q^2 n_1 0.360 $2pq^2$ n_{11} 0.288 $2p^2q$ n_{111} 0.192 p^2 n_{12} 0.160	probabilityFrequency $p=0.4$ $p=0.7$ q^2 n_1 0.3600.090 $2pq^2$ n_{11} 0.2880.126 $2p^2q$ n_{111} 0.1920.294 p^2 n_{12} 0.1600.490

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─の�?



 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

$Chain\ binomial\ model$

- Data: The observations are based on outbreaks of measles in Rhode Island 1929–1934.
- The analysis is restricted to N = 334 families with three susceptible individuals at the outset of the epidemic.
- Assume there is a single index case that introduces infection into the family.
- The actual chains are not observed, just how many are infected at the end of the epidemic.
- So the frequency of chains $1\longrightarrow 1\longrightarrow 1$ and $1\longrightarrow 2$ are not observed.
- MCMC can be used to augment the missing data, and estimate the transmission probability *p*.

 TRANSMISSION PROBABILITY 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

Chain Binomial Model

Table : Rhodes Island measles data: chain binomial probabilities in the Reed-Frost model in N = 334 households of size 3 with 1 initial infective and 2 susceptibles, $N_3 = n_{111} + n_{12} = 275$ is observed

			Final
Chain		Observed	number
probability	Frequency	frequency	infected
q^2	<i>n</i> ₁	34	1
2pq ²	<i>n</i> ₁₁	25	2
2p ² q	<i>n</i> ₁₁₁	not observed	3
<i>p</i> ²	<i>n</i> ₁₂	not observed	3
1	Ν	334	
	probability q^2 $2pq^2$	probability Frequency q^2 n_1 $2pq^2$ n_{11} $2p^2q$ n_{111}	probabilityFrequencyfrequency q^2 n_1 34 $2pq^2$ n_{11} 25 $2p^2q$ n_{111} not observed p^2 n_{12} not observed

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ = 差 = のへで



 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

General epidemic (SIR) model

- The population of *N* individuals
- Denote the numbers of susceptible, infective, and removed individuals at time t by S(t), I(t), and R(t).
- The process can be represented by the compartmental diagram

$$S(t) \longrightarrow I(t) \longrightarrow R(t)$$

- Thus, S(t) + I(t) + R(t) = N for all t.
- Initially, (S(0), I(0), R(0)) = (N 1, 1, 0)

 Transmission Probability 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

General epidemic model

- Each infectious individual remains so for a length of time $T_I \sim \exp(\gamma)$.
- During this time, infectious contacts occur with each susceptible according to a Poisson process of rate β/N
- Thus, the overall hazard of infection at time t is $\beta I(t)/N$
- The two model parameters of interest are β and γ



 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

General epidemic model

- In a well-known smallpox data set, the removal times are observed. That is, when the people are no longer infectious for others.
- However, the infection times are not observed.
- Thus, estimating the two model parameters is difficult.
- The missing infection times are treated as latent variables.
- MCMC methods are used to augment the missing infection times and estimate the parameters β and γ .

 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Susceptible-infected-susceptible (SIS) model

- Background: Many infections are recurrent, occurring as an alternating series of presence and absence of infection
- Nasopharyngeal carriage of *Streptococcus pneumoniae* (Auranen et al 2000; Cauchemez et al; Melegaro et al)
- Nasopharyngeal carriage of *Neisseria meningitidis* (Trotter and Gay 2003)
- Malaria (Nagelkerke et al,)
- multi-resistant Staphylococcus aureus (Cooper et al)

 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Susceptible-infected-susceptible (SIS) model

- The population of N individuals
- Denote the numbers of susceptible and infected individuals at time t by S(t) and I(t).
- The process can be represented by the compartmental diagram

 $S(t) \leftrightarrow I(t)$

- Thus, S(t) + I(t) = N for all t.
- Acquisition and clearance times often remain unobserved
- Active sampling of the population to determine the current status of being infected or susceptible in individuals.

INTRODUCTION 00000 000000000000 0000 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Susceptible-infected-susceptible (SIS) model

- Could be formulated as an infectious disease transmission process, as the general epidemic model.
- Too complicated for this introductory course
- We consider here the simple transition process, with rate parameters λ for acquisition and μ for clearance.
- The acquisition and clearance times are treated as latent variables.
- MCMC methods are used to augment the missing infection and clearance times, and estimate the parameters λ and μ .

Transmission Probability 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

◆□▶ ◆□▶ ◆□▶ ◆□▶ ●□

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Conjugate prior distributions

- Conjugacy: the property that the posterior distribution follows that same parametric form as the prior distribution.
- Beta prior distribution is conjugate family for binomial likelihood: posterior distribution is Beta
- Gamma prior distribution is conjugate family for Poisson likelihood: posterior distribution is Gamma

TRANSMISSION PROBABILITY 000000 000 SIMPLE GIBBS SAMPLER 000000 000000

Conjugate prior distributions

- Simply put, conjugate prior distributions in tandem with the appropriate sampling distribution for the data have the same distribution as the posterior distribution.
- Conjugate prior distributions have computational convenience.
- They can also be interpreted as additional data.
- They have the disadvantage of constraining the form of the prior distribution.

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Nonconjugate prior distributions

- Nonconjugate prior distributions can be used when the shape of the prior knowledge or belief about the distribution of the parameters of interest does not correspond to the conjugate prior distribution.
- Noninformative prior distributions carry little population information and are generally supposed to play a minimal role in the posterior distribution.
 - \longrightarrow They are also called diffuse, vague, or flat priors.
- Computationally nonconjugate distributions can be more demanding.

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY •00000 000 000

SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰 ト ▲ ヨ ト ▲ ヨ ト ・ ヨ ・ の Q ()

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals



INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Data and Sampling Distribution

- Goal: Inference on the posterior distribution of the transmission probability
- Suppose that *n* people are exposed once to infection
 - y become infected ("successes")
 - n y escape infection ("failures")

Let

- *p* = transmission probability
- 1 p = q = escape probability
- Binomial sampling distribution

$$L(y|p) = \operatorname{Bin}(y|n,p) = \binom{n}{y} p^{y} (1-p)^{n-y} = \binom{n}{y} p^{y} q^{n-y}$$

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Specify the Prior Distribution of p

- To perform Bayesian inference, we must specify a prior distribution for *p*.
- We specify a Beta prior distribution:

$$p \sim \text{Beta}(\alpha, \beta)$$

$$\mathsf{Beta}(p|\alpha,\beta) = \frac{\mathsf{\Gamma}(\alpha+\beta)}{\mathsf{\Gamma}(\alpha)\mathsf{\Gamma}(\beta)}p^{\alpha-1}(1-p)^{\beta-1}, \alpha > 0, \beta > 0.$$

• Mean:
$$E(p|\alpha,\beta) = \frac{\alpha}{\alpha+\beta}$$

• Variance:
$$\frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)} = \frac{E(p|\alpha,\beta)[1-E(p|\alpha,\beta)]}{\alpha+\beta+1}$$

◆□▶ ◆□▶ ◆三▶ ◆三▶ ○□ のへで

INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

Specify the Prior Distribution of p

• We specify a Beta prior distribution:

$$p \sim \operatorname{Beta}(lpha, eta)$$

$$\pi(p) = \text{Beta}(p|\alpha,\beta)$$

Beta
$$\propto p^{lpha-1}(1-p)^{eta-1}$$

- · Looks similar to binomial distribution
- $\alpha > 0$, $\beta > 0$, "prior sample sizes"



INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

Posterior distribution of p

The posterior distribution of the transmission probability p,
 f(p|y):

$$f(p|y) \propto p^{y}(1-p)^{n-y}p^{\alpha-1}(1-p)^{\beta-1}$$

posterior likelihood \times prior

$$= p^{y+\alpha-1}(1-p)^{n-y+\beta-1}$$

=
$$Beta(p|\alpha + y, \beta + n - y)$$

• The role of α and β as prior sample sizes is clear.

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰 ト ▲ ヨ ト ▲ ヨ ト ・ ヨ ・ の Q ()

Posterior mean of θ

• Posterior mean of p

 \longrightarrow posterior probability of success (transmission) for a future draw from the population:

$$\mathsf{E}(p|y) = \frac{\alpha + y}{\alpha + \beta + n}$$

- posterior mean always lies between the prior mean $\alpha/(\alpha + \beta)$ and the sample mean y/n.
- Posterior variance of *p*:

$$\operatorname{var}(p|y) = \frac{E(p|y)[1 - E(p|y)]}{\alpha + \beta + n + 1}$$

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰 ト ▲ ヨ ト ▲ ヨ ト ・ ヨ ・ の Q ()

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

INTRODUCTION 00000 00000000000000 0000 SIMPLE GIBBS SAMPLER 000000 000000

Uniform prior distribution

• The uniform prior distribution on [0,1] corresponds to $\alpha = 1$, $\beta = 1$. Essentially no prior information on *p*.

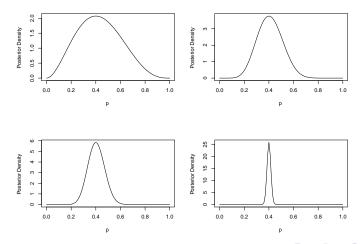
$$f(p|y) = \mathsf{Beta}(p|y+1, n-y+1)$$

• Let's see how the posterior distribution of the transmission probability depends on the amount of data given a uniform prior distribution (Sample mean y/n = 0.40).

n, number exposed	y, number infected
5	2
20	8
50	20
1000	400

JTLINE	INTRODUCTION	TRANSMISSION PROBABILITY	Simple Gibbs sampler
	00000 000000000000 0000	000000 000 0000	000000

Figure : R program: Posterior distribution with differing amounts of data. Uniform Beta prior, Binomial sampling distribution.



▲口→ ▲圖→ ▲臣→ ▲臣→ 三臣 …

~) Q (*

TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

▲ロト ▲帰ト ▲ヨト ▲ヨト - ヨ - の々ぐ

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

0				
U	Ŧ		18	E

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

Prediction

- After the data have been observed, we can predict a future unknown observable y_{n+1} .
- For example, we may observe *n* people who were exposed to infection, and whether they became infected.
- We may want to predict the probability that the next person to be observed would become infected.
- Posterior predictive distribution:
 - \longrightarrow posterior because conditional on the observed y
 - \longrightarrow predictive because it is a prediction for an observable y_{n+1} .

0		~		
U	T			

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

Prediction

• Posterior predictive distribution of unknown observable y_{n+1} :

$$f(y_{n+1}|y) = \int f(y_{n+1}, p|y)dp$$

= $\int f(y_{n+1}|p, y)f(p|y)dp$
= $\int f(y_{n+1}|p)f(p|y)dp$

- The last line follows because y and y_{n+1} are conditionally independent given p in this model.
- Useful in model checking.



TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQ@

References

- Gelman, A, Carlin, JB, Stern, HS, Dunson, DB, Vehtari, A, Rubin, DB. *Bayesian Data Analysis*, Chapman and Hall/CRC, third edition, 2014.
- Carlin, BP and Louis, TA. *Bayesian Methods for Data Analysis*, CRC Press, third edition, 2008.

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY 0000000 000 0000 SIMPLE GIBBS SAMPLER ••••••• •••••••

◆□▶ ◆□▶ ◆□▶ ◆□▶ ●□

Introduction

Bayesian inference Motivating examples Prior distributions

Transmission Probability

Full probability model Varying data and prior information Prediction

Simple Gibbs sampler

Chain binomial model Full conditionals

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER 000000 000000

Chain Binomial Model

Table : Rhodes Island measles data: chain binomial probabilities in the Reed-Frost model in N = 334 households of size 3 with 1 initial infective and 2 susceptibles, $N_3 = n_{111} + n_{12} = 275$ is observed

			Final
Chain		Observed	number
probability	Frequency	frequency	infected
q^2	<i>n</i> ₁	34	1
2pq ²	<i>n</i> ₁₁	25	2
2p ² q	<i>n</i> ₁₁₁	not observed	3
<i>p</i> ²	<i>n</i> ₁₂	not observed	3
1	Ν	334	
	probability q^2 $2pq^2$	probability Frequency q^2 n_1 $2pq^2$ n_{11} $2p^2q$ n_{111}	probabilityFrequencyfrequency q^2 n_1 34 $2pq^2$ n_{11} 25 $2p^2q$ n_{111} not observed p^2 n_{12} not observed

◆□ ▶ ◆□ ▶ ◆臣 ▶ ◆臣 ▶ ○ 臣 ○ ○ ○ ○



INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER

Complete data likelihood for q

• The multinomial complete data likelihood for q:

 $f(n_1, n_{11}, N_3, n_{111}|q)$

$$= \begin{pmatrix} 334\\ n_1, n_{11}, n_{111}, N_3 - n_{111} \end{pmatrix} (q^2)^{n_1} (2q^2p)^{n_{11}} (2qp^2)^{n_{111}} (p^2)^{N_3 - n_{111}}$$
$$= \text{constant} \times q^{2n_1 + 2n_{11} + n_{111}} p^{n_{11} + 2N_3}$$

- The observed data are (n_1, n_{11}, N_3) , but we do not observe n_{111} .
- We could estimate q using a marginal model, but won't.

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER

Gibbs sampler for chain binomial model

- The general idea of the Gibbs sampler is to sample the model unknowns from a sequence of full conditional distributions and to loop iteratively through the sequence.
- To sample one draw from each full conditional distribution at each iteration, it is assumed that all of the other model quantities are known at that iteration.
- In the theoretical lectures, it will be shown that that the Gibbs sampler converges to the posterior distribution of the model unknowns.
- In the Rhode Island measles data, we are interested in augmenting the missing data n_{111} and estimating the posterior distribution of q, the escape probability.

TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER

Gibbs sampler for chain binomial model

- The joint distribution of the observations (n_1, n_{11}, N_3) and the model unknowns (n_{111}, q) is

$$\begin{array}{ll} f(n_1, n_{11}, N_3, n_{111}, q) &= f(n_1, n_{11}, N_3, n_{111} | q) \times f(q) \\ & \quad \text{complete data likelihood } \times \text{ prior} \end{array}$$

• We want to make inference about the joint posterior distribution of the model unknowns

$$f(n_{111}, q | n_1, n_{11}, N_3)$$

• This is possible by sampling from the full conditionals (Gibbs sampling): $f(q|n_1, n_{11}, N_3, n_{111})$ and $f(n_{111}|n_1, n_{11}, N_3, q)$

INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY 0000000 000 0000 SIMPLE GIBBS SAMPLER

Algorithm for Gibbs sampler for chain binomial model

- 1. Start with some initial values $(q^{(0)}, n_{111}^{(0)})$
- 2. For t = 0 to M do
- 3. Sample $q^{(t+1)} \sim f(q|n_1, n_{11}, N_3, n_{111}^{(t)})$
- 4. Sample $n_{111}^{(t+1)} \sim f(n_{111}|n_1, n_{11}, N_3, q^{(t+1)})$
- 5. end for
- 6. How to get the two full conditionals in this model?

INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQ@

Full conditional of chain $1 \longrightarrow 1 \longrightarrow 1$

- Assume q is known
- Compute the conditional probability of chain $1 \rightarrow 1 \rightarrow 1$ when outbreak size is N = 3:

$$\Pr(1 \to 1 \to 1 | N = 3, q) = \frac{\Pr(N = 3, 1 \to 1 \to 1 | q)}{\Pr(N = 3 | q)}$$
$$= \frac{\Pr(N = 3 | 1 \to 1 \to 1, q) \Pr(1 \to 1 \to 1 | q)}{\Pr(N = 3 | 1 \to 1 \to 1, q) \Pr(1 \to 1 \to 1 | q) + \Pr(N = 3 | 1 \to 2, q) \Pr(1 \to 2 | q)}$$
$$= \frac{2p^2q}{2p^2q + p^2} = \frac{2q}{2q + 1}, \quad (0 \le q < 1)$$

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY

SIMPLE GIBBS SAMPLER

The full conditional of n_{111}

• We have found that

$$\mathsf{Pr}(1
ightarrow 1
ightarrow 1 | \mathsf{N} = 3, q) = rac{2q}{2q+1}$$

• So the full conditional distribution of n_{111} is

 $n_{111}|(n_1, n_{11}, N_3, q) \sim \text{Binomial}(275, 2q/(2q+1))$

INTRODUCTION 00000 00000000000000 0000 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER

The full conditional of q

- Assume that n_{111} is known, that is, assume we know the complete data $(n_1, n_{11}, N_3, n_{111})$
- Assume a prior distribution for $q: q \sim \text{Beta}(\alpha, \beta)$,

$$f(q) \equiv f(q|lpha,eta) \propto q^{lpha-1}(1-q)^{eta-1}$$

• The full conditional distribution of q :

 $f(q|n_1, n_{11}, N_3, n_{111}, \alpha, \beta) \propto f(n_1, n_{11}, N_3, n_{111}|q, \alpha, \beta) f(q|\alpha, \beta)$

$$\propto q^{2n_1+2n_{11}+n_{111}}p^{n_{11}+2N_3} imes q^{lpha-1}(1-q)^{eta-1}$$
 complete data likelihood $imes$ prior



TRANSMISSION PROBABILITY 0000000 000 00000 SIMPLE GIBBS SAMPLER

The full conditional of q

• The full conditional distribution of *q* is thus a Beta distribution

q|complete data, $\alpha, \beta \sim \text{Beta}(2n_1 + 2n_{11} + n_{111} + \alpha, n_{11} + 2N_3 + \beta)$

- A uniform prior on q corresponds to $\alpha = 1$, $\beta = 1$.
- With the complete data, a natural point estimate of the escape probability would be the mean of the Beta distribution, i.e., the proportion of "escapes" out of all exposures:

$$\frac{2n_1 + 2n_{11} + n_{111} + \alpha}{2n_1 + 3n_{11} + 3n_{111} + 2n_{12} + \alpha + \beta}$$

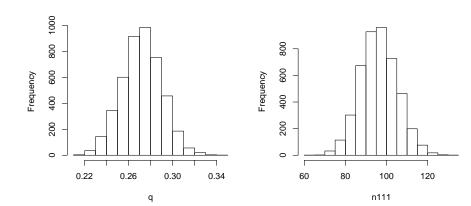
INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY 0000000 000 0000 SIMPLE GIBBS SAMPLER

Algorithm for Gibbs sampler for chain binomial model

- 1. Start with some initial values $(q^{(0)}, n_{111}^{(0)})$
- 2. For t = 0 to M do
- 3. Sample $q^{(t+1)} \sim \text{Beta}(2n_1 + 2n_{11} + n_{111}^{(t)} + \alpha, n_{11} + 2N_3 + \beta)$
- 4. Sample $n_{111}^{(t+1)} \sim \text{Binomial}(275, 2q^{(t+1)}/(2q^{(t+1)}+1))$
- 5. end for
- 6. Get summaries of the marginal posterior distributions.

INTRODUCTION 00000 0000000000000 0000 TRANSMISSION PROBABILITY 000000 000 0000 SIMPLE GIBBS SAMPLER

Posterior distributions of q and n_{111}



◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 = のへ⊙